

# Reasoning and Planning

## Unit 1. Introduction

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- 1 History and Motivation
- 2 Knowledge Representation goals
- 3 Knowledge Representation areas

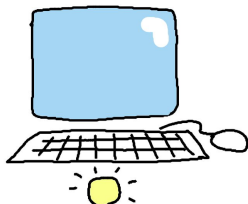
- Define Automated Reasoning
- Define Automated Planning
- Define Knowledge Representation (KR)
- Identify systems or applications where they might be used
- Pros and Cons

# The origins of KR



John McCarthy (1927-2011)

- Coins the term **Artificial Intelligence**  
*“It is the science and engineering of making intelligent machines, especially intelligent computer programs”*





John McCarthy (1927-2011)

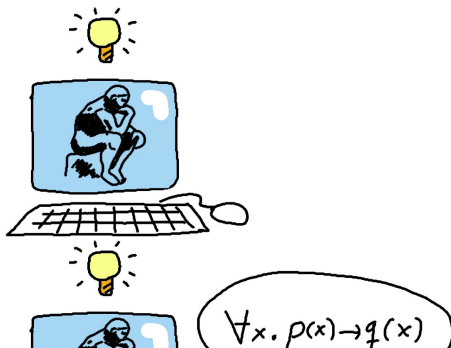
- *Programs with Commonsense* [1959].  
<http://jmc.stanford.edu/articles/mcc59.html>  
First AI reasoning system: **Advice Taker**.
- Keypoint: **explicit representation** of the domain using **logical formulas**. In McCarthy's words:  
*"In order for a program to be capable of learning something it must first be capable of **being told it**"*

# The origins of KR



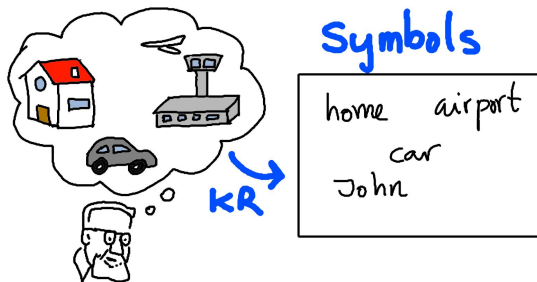
John McCarthy (1927-2011)

- Novel idea: using **formal logic** for **commonsense reasoning**



# Reasoning about Actions and Change (RAC)

- Knowledge Representation (KR) plays a **central role** in AI.



- Automated reasoning**: mechanization of thinking.  
Inference = **manipulation of symbols** in the machine.
- Example: Modus Ponens

$at(John, car) \rightarrow can(go(home, airport, driving))$        $at(John, car)$   
 $can(go(home, airport, driving))$

# Reasoning about Actions and Change (RAC)

- Commonsense reasoning led to the KR area called Reasoning about Actions and Change.
- *Some philosophical problems from the standpoint of Artificial Intelligence* [McCarthy & Hayes 69]

<http://jmc.stanford.edu/articles/mcchay69.html>

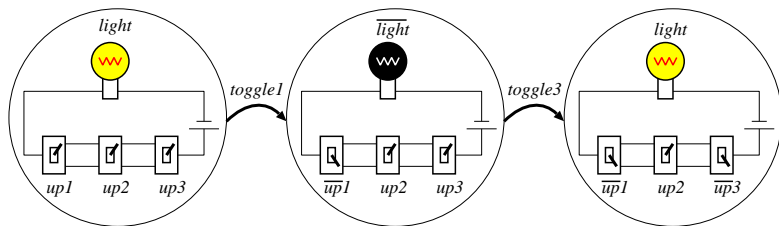
They introduce Situation Calculus = First Order Logic + 3 sorts:

- 1 **Fluents**: system properties whose values may vary along time. These values configure the system state.
- 2 **Actions**: possible operations that allow a state transition.
- 3 **Situations**: terms that identify a given instant



# RAC scenarios

- Typically, (discrete) dynamic systems: **state transitions**.
- A simple scenario: a lamp in a corridor with 3 switches.
- **Fluents**:  $up1, up2, up3, light$  (Boolean).
- **Actions**:  $toggle1, toggle2, toggle3$ .
- **State**: a possible configuration of fluent values. Example:  $\{\overline{up1}, up2, \overline{up3}, \overline{light}\}$ .
- **Situation**: a moment in time. We can just use  $0, 1, 2, \dots$



We want to solve some **typical reasoning problems**.

The most usual ones:

- **Simulation**: run a sequence of actions on an initial state
- **Temporal explanation**: fill gaps from partial observations
- **Planning**: obtain sequence of actions to reach some goal
- **Diagnosis**: explain unexpected observed results
- **Verification**: check system properties

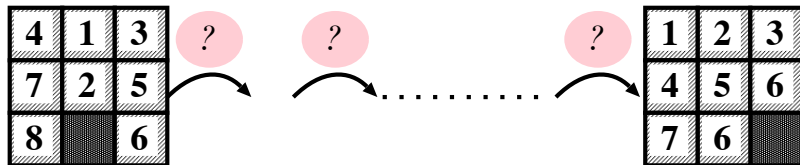
## AI Methodology



- Paraphrasing McCarthy's comment in a workshop:  
*AI researchers start from examples and then try to generalize. Philosophers start from the most general case, and never use examples unless they are forced to.*
- Advantage: focus on features under study using a synthetic, limited scenario (games, puzzles, etc)
- Real problems usually contain complex factors that happen to be irrelevant for the property under study.

# Example-based methodology

- A classical (planning) example: the  $N$ -puzzle.



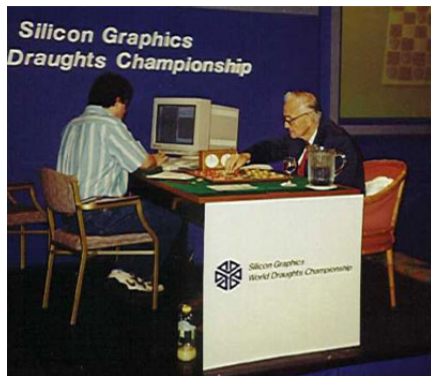
- Well known: the 8-puzzle has 181440 states, the 15-puzzle more than  $10^{13}$ .
- Complexity: NP-complete.



Alexander Kronrod (1921-1986)

- “Chess is the *Drosophila* of AI” [A. Kronrod 65]
- Games for AI can play the same role as *fruit flies* for Genetics.
- Competition: AI versus humans . . .

# Example-based methodology



1994: [Chinook](#) [J. Schaeffer] checkers program  
beats world champion Marion Tinsley

# Example-based methodology



1997: IBM Deep Blue beats Chess World Champion Garry Kasparov

# Example-based methodology



2016: **AlphaGo** beats Go  
World Champion Lee Sedol



# Example-based methodology

- Still, we don't have intelligent (rational) machines yet
- Warning: avoid too much focus on the toy problem. Remember we must be **capable of generalizing** the obtained results.
- Back to the chess example:  
*“Unfortunately, the competitive and commercial aspects of making computers play chess have taken precedence over using chess as a scientific domain. It is as if the geneticists after 1910 had organized **fruit fly races** and concentrated their efforts on breeding fruit flies that could win these races.” [McCarthy]*

# Example-based methodology

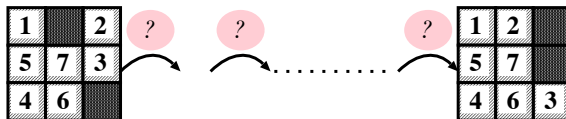
- Take the 8-puzzle example. Which is our **main goal**? Making a very **fast solver** for 8-puzzle?



- But what can we learn from that? Which is the application to **other scenarios**?
- We should perhaps wonder **which other scenarios**. Originally, AI goal was **any scenario** (General Problem Solver) but was too ambitious.
- It could perhaps suffice with **similar scenarios**. Small variations or **elaborations**.

# Elaboration

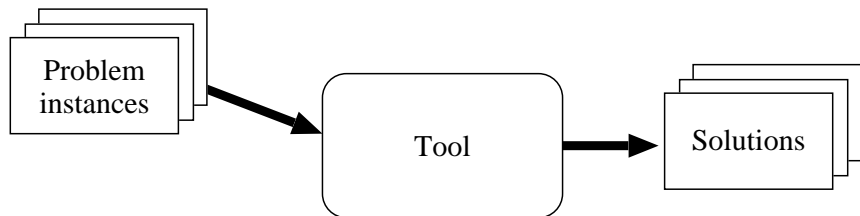
- Example: assume we may allow now **two holes**.



- Less steps to solve. We can even allow simultaneous movements.
- Can we **easily adapt** our solver to this elaboration?
- Think about an optimized heuristic search algorithm programmed in C, for instance.

# Keypoint: representation

- A much more flexible solution:  
add a **description of the scenario** as an **input** to our solver.
- In this way, variations of the scenario would mean changing the problem description . . . **Knowledge Representation** (KR) is crucial!
- An **explicit representation** of the domain rules allows **Declarative Problem Solving**:



- 1 History and Motivation
- 2 Knowledge Representation goals**
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# Keypoint: representation

- Which are the desirable properties of a good KR?
  - 1 Simplicity
  - 2 Natural understanding: correspondence with human language
  - 3 Clear semantics
  - 4 Allows efficiently computable automated reasoning methods or at least, their complexity can be assessed
  - 5 Elaboration tolerance [McCarthy98]

*“A formalism is elaboration tolerant to the extent that it is convenient to modify a set of facts expressed in the formalism to take into account new phenomena or changed circumstances.”*  
[McCarthy98]

# Elaboration tolerance

“Elaborating Missionaries and Cannibals Problem” [J. McCarthy]

<http://jmc.stanford.edu/articles/missionaries1.html>

*3 missionaries and 3 cannibals come to a river and find a boat that holds two. If the cannibals ever outnumber the missionaries on either bank, the missionaries will be eaten. How shall they cross?*



- McCarthy proposes 22 elaborations of the problem: MCP4=four on each group; MCP5=missionaries can't row; MCP10=there is an island; MCP11=Jesus Christ; MCP15=probabilities . . .

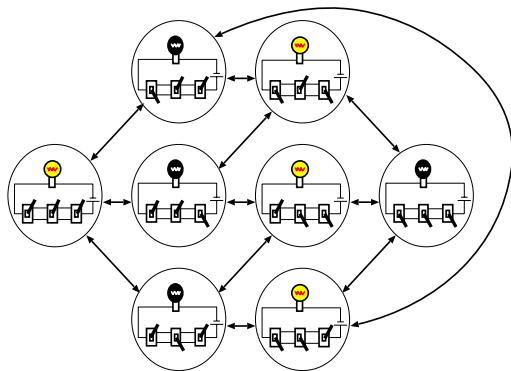
# Elaboration tolerance

- Students A and B encode the 8 puzzle as follows:
  - ▶ Student A:  
 $at(1, 1, 8) \quad at(1, 2, 6) \quad at(1, 3, hole) \dots$
  - ▶ Student B:  
 $row(8) = 1 \quad col(8) = 1$   
 $row(6) = 1 \quad col(6) = 2$   
 $row(hole) = 1 \quad col(hole) = 3$
- Add more holes: which solution is **more elaboration tolerant**?  
Solution A requires **no changes**!
- The real problem comes when **our KR formalism has no way** to find an elaboration tolerant solution



# Elaboration tolerance

- Example of representation: an **automaton** is simple, and has a clear semantics ...
- But **fails in elaboration tolerance!** A small change (say, adding new switches or lamps) means **a complete rebuilding**



# Keypoint: representation

- A practical alternative: use rules to describe the **local effects** of each performed action.
- For each switch  $X \in \{1, 2, 3\}$

	Action	precondition	$\Rightarrow$ effect(s)
	$toggle(X)$	$up(X)$	$\Rightarrow \overline{up(X)}$
	$toggle(X)$	$\overline{up(X)}$	$\Rightarrow up(X)$
	$toggle(X)$	$light$	$\Rightarrow \overline{light}$
	$toggle(X)$	$\overline{light}$	$\Rightarrow light$

- This language is similar to STRIPS [Fikes & Nilsson 71] still used in planning systems.

- Can we just use **classical logic** instead?

$$\begin{aligned} \text{toggle}(X) : \text{up}(X) &\Rightarrow \overline{\text{up}(X)} \\ \text{toggle}(X, T) \wedge \text{up}(X, \text{true}, T - 1) &\rightarrow \text{up}(X, \text{false}, T) \end{aligned}$$

where we include as new arguments, the temporal indices  $T > 0, T - 1$  plus the fluent values *true, false*.

- **Problem:** when *toggle(1)*, what can we conclude about *up(2)* and *up(3)*?

They should **remain unchanged!** However, our logical theory provides no information (we also have models where their value change).

- We would need much more formulae

$$\begin{aligned} \text{toggle}(1, T) \wedge \text{up}(2, \text{true}, T - 1) &\rightarrow \text{up}(2, \text{true}, T) \\ \text{toggle}(1, T) \wedge \text{up}(2, \text{false}, T - 1) &\rightarrow \text{up}(2, \text{false}, T) \end{aligned}$$

$$\begin{aligned} \text{toggle}(1, T) \wedge \text{up}(3, \text{true}, T - 1) &\rightarrow \text{up}(3, \text{true}, T) \\ \text{toggle}(1, T) \wedge \text{up}(3, \text{false}, T - 1) &\rightarrow \text{up}(3, \text{false}, T) \end{aligned}$$

⋮

and so on, for any fluent and value that are unrelated to  $\text{toggle}(1)$ .

# Default reasoning

- **Frame problem**: adding a simple fluent or action means reformulating all these formulae! [McCarthy & Hayes 69]
- We need a kind of **default reasoning**.  
**Inertia rule**: fluents remain unchanged *by default*
- “By default” = when no evidence on the contrary is available. We must extract **conclusions from absence of information**.
- Unfortunately, Classical Logic is not well suited for this purpose because

$$\Gamma \vdash \alpha \text{ implies } \Gamma \cup \Delta \vdash \alpha$$

This is called **monotonic** consequence relation.

- But  $\Gamma \vdash \alpha$  by default could mean that adding  $\Delta$ ,  $\Gamma \cup \Delta \not\vdash \alpha$ .  
We need **Nonmonotonic Reasoning** (NMR).

# Default reasoning

- An example: suppose  $up(2, true, 0)$  and we perform  $toggle(1, 0)$ . Inertia should allow us to conclude that switch 2 is unaffected:

$$\Gamma \vdash up(2, true, 1)$$

- Elaboration: we are said now that  $toggle(1)$  affects  $up(2)$  in the following way:

$$toggle(1, T) \wedge up(2, true, T - 1) \rightarrow up(2, false, T) \quad (1)$$

We will need **retract** our previous conclusion

$$\Gamma \cup (1) \not\vdash up(2, true, 1)$$

# Other typical representational problems

- **Qualification problem**: preconditions are affected by conditions that **qualify** an action.
- Example: when can we toggle the switch? Elaborations: switch is not broken, switch has not been stuck, we must be close enough, etc.
- The explicit addition of any imaginable “disqualification” is unfeasible. Again: **by default**, toggle works when nothing prevents it.

# Other typical representational problems

- Elaboration: there is a light sensor that activates an alarm, if the latter is connected. The alarm causes locking the door.
- In STRIPS, this means relating indirect effects *alarm* to each possible action *toggle(X)*.

Action	precondition	⇒ effect(s)
<i>toggle(X)</i>	$\overline{light}, connected$	<i>alarm</i>
<i>toggle(X)</i>	$\overline{light}, connected$	<i>lock</i>

Problem: there may be other new ways to turn on a light, or to activate the alarm. We will be forced to relate *lock* to the performed actions!



# Other typical representational problems

- This is called **ramification problem**: postconditions are affected by interactions due to **indirect effects**.
- *lock* is an **indirect effect** of toggling a switch (*toggle*  $\mapsto$  *light*  $\mapsto$  *alarm*  $\mapsto$  *lock*).
- We would need something like:

$$\begin{aligned} \textit{light}(\textit{true}, T) \wedge \textit{connected}(\textit{true}, T) &\rightarrow \textit{alarm}(\textit{true}, T) \\ \textit{alarm}(\textit{true}, T) &\rightarrow \textit{lock}(\textit{true}, T) \end{aligned}$$

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Main conferences including KR, Reasoning and Planning

- **IJCAI**: Intl. Joint Conf. on Artificial Intelligence
- **AAAI**: Conf. on Artificial Intelligence
- **ECAI**: European Conf. on Artificial Intelligence
- **KR**: Intl. Conf. on Principles of Knowledge Representation and Reasoning
- **ICAPS**: Intl. Conf. on Automated Planning and Scheduling
- **IJCAR**: Intl. Joint Conf. on Automated Reasoning
- **JELIA**: European Conf. on Logics in Artificial Intelligence
- **LPNMR**: Intl. Conf. on Logic Programming and Non-Monotonic Reasoning LPNMR'13 celebrated in Corunna!
- Workshop on Logical Formalizations of Commonsense Reasoning

# KR is a well-established field

These are some of the usual topics in KR call for papers:

- Reasoning about **actions and change**, dynamic logic
- **Epistemic reasoning** (knowledge and belief)
- **Belief revision and update**
- Explanation finding, **diagnosis**, **causal** reasoning, abduction
- **Nonmonotonic logics**, default logics, conditional logics
- (Constraint) logic programming, **answer set programming**
- Qualitative reasoning, **spatial** reasoning and **temporal** reasoning
- **Argumentation**
- **Computational** aspects of KR, **complexity**
- Description logics, **ontology** languages, contextual reasoning
- Inconsistency, **paraconsistent** logics
- **Preference** modeling and representation
- **Philosophical** foundations of KR
- **Uncertainty**, vagueness, many-valued and fuzzy logics, relational probability