

Introduction

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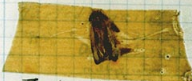
2015/2016

Bugs

9/9

0800 Antenn started
 1000 " stopped - antenn ✓
 1300 (032) MP - MC { 1.2700 9.037 847 025
 (033) PRO 2 2.130476415 9.037 846 995 correct
 correct 2.130476415
 Relays 6-2 in 033 failed special speed test
 in relay 10,000 test.

1100 Relays changed
 Started Cosine Tapc (Sine check)
 1525 Started Multy Adder Test.

1545  Relay #70 Panel F
 (moth) in relay.

First actual case of bug being found.
 1630 Antenn started.
 1700 closed down.

Relay 3145
 Relay 3376

The first **real bug** detected in Harvard Mark II

Introduction

- Software is a **complex, conceptual product** \Rightarrow **Errors are inherent**
- Software may be **faulty** or work **unexpectedly**.



Facing a program, a pair of natural questions are:

- **Faulty**: is this program **right**? \Rightarrow **verification**
- **Unexpected**: is this **the right** program? \Rightarrow **validation**

Let us focus on **verification** ...

An example

- We want to compute the greatest common divisor of two integers $x > y > 0$, $\text{gcd}(x, y)$
- The following code is obviously correct:

```
gcd:=1;  
for i:=2 to y do  
  if ((x mod i)=0) and ((y mod i)=0) then  
    gcd:=i;
```

but rather **inefficient**. How many steps do we need for $\text{gcd}(10000000, 1000000)$?

An example

- Euclid's algorithm [Euclid, 300 BC]:

```
a:=x;  
b:=y;  
while a<>b do begin  
  if a>b then  
    a:=a-b  
  else  
    b:=b-a;  
end;  
gcd:=a;
```

- Obviously faster but ...

Exercise 1 (0,6 points T.G.R.)

Can you prove it is *correct*? (if not, a real shock after 2.300 years!)

A bit of history ...

- During the 1960's **algorithm design** was born.
- But up to late 60's: unreadable programs, **GOTO** statements.
So-called "**spaghetti code**"

```
10 i = 0
20 i = i + 1
30 PRINT i; " squared = "; i * i
40 IF i >= 10 THEN GOTO 60
50 GOTO 20
60 PRINT "Program Completed."
70 END
```

- **Structured programming** [Böhm & Jacopini 66]:
any program = {sequential + conditional + iterative} instructions.

```
for i:=1 to 10 do
    writeln(i, ' squared= ', i*i);
writeln('Program completed');
```



John McCarthy
(1927 – 2011)

Turing Award 1971

- [McCarthy 1951] "*A basis for a Mathematical Theory of Computation*" actually the first proposal of replacing trial-and-error by **formal proof** of correctness.
- [McCarthy 1960] "*Recursive Functions of Symbolic Expressions and Their Computation by Machine, Part I*" = **LISP** language.
- McCarthy introduced the first example of program semantics (**operational semantics**) using **lambda calculus** for LISP.

Formal reasoning in AI



Allen Newell
(1927 – 1992)

Turing Award 1975



Herbert Simon
(1916 – 2001)

Turing Award 1975

Nobel (Economics) 1978

- [Herbert & Simon 1955] **Logic Theorist**: probably the first successful theorem prover (proved 38 theorems from Russell's Principia Mathematica)



Sir C. Anthony R. Hoare (1934 –)

Turing Award 1980

- [H. 1962] designs the Quicksort algorithm. Was it correct? crucial point: defining a program semantics
- [H. 1969] Hoare Logic (axiomatic semantics).

$\{Q\} \text{ prog } \{R\}$ = If precondition Q initially true,
then program **prog** terminates
satisfying postcondition R .

*“There are two ways of constructing a piece of software:
One is to make it so simple that there are obviously no errors,
and the other is to make it so complicated that there are no
obvious errors.” Tony Hoare.*



Edsger W. Dijkstra (1930 – 2002)

Turing Award 1972

- [D. 1959] algorithm for **shortest path tree**.
- [D. 1965] introduces the idea of **semaphore** for controlling shared resources in a concurrent environment.
- [D. 1968] *Go To Statement Considered Harmful*.
- [D. 1976] *A Discipline of Programming*:
formal verification, **weakest precondition**, **program derivation**,
guarded commands programming language.



Dana S. Scott (1932 –)

Turing Award 1976

- [Scott & Rabin 1959] “*Finite Automata and Their Decision Problems*” (nondeterministic machines, automata theory)
- [Scott & Strachey 1971] “*Toward a mathematical semantics for computer languages*” **denotational semantics**.
“**Denotation**” = function from input to output.
- A semantics is **compositional** when the meaning of a sentence is built on the meaning of its sub-sentences \Rightarrow basis of **functional languages with concurrency** (e.g. Haskell).

Verification

- **Verification**: prove or disprove the **correctness** of a given system: **software** (algorithms, protocols) or **hardware** (circuits).
- Checking that the program is **correct** ... but when? **always**, **sometimes**, **in a given case**?

- ▶ **Always** correct: prove a **necessary** and **sufficient** condition

The program is correct if and only if:

$$x \bmod a = 0 \wedge y \bmod a = 0$$

$$\wedge \neg \exists z > a (x \bmod z = 0 \wedge y \bmod z = 0)$$

- ▶ **Sometimes** correct: prove a **necessary** condition.

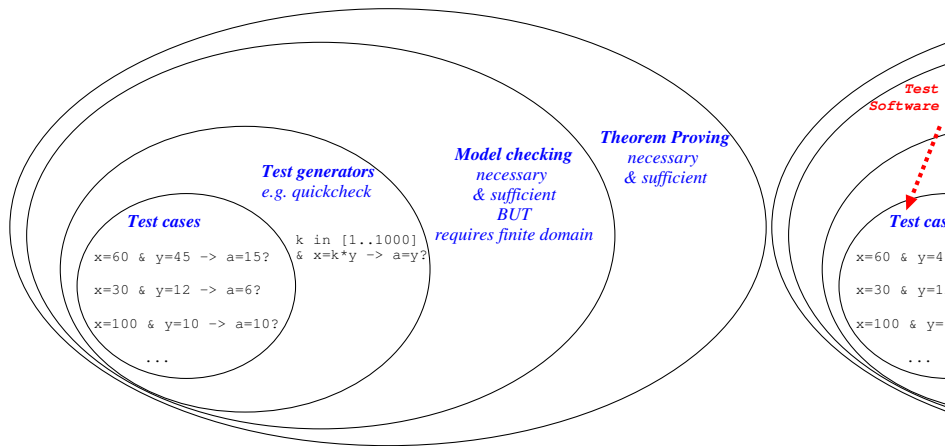
If the program is correct, it must satisfy:

$$x = k * y \Rightarrow a = y$$

- ▶ Correct for some **test case** (a stronger **necessary** condition). Try this test:

$$x = 60 \wedge y = 45 \Rightarrow a = 15$$

Verification



- Formal methods

- ① Formal **specification**: formulas asserting **what** the system should do, not **how**.
- ② Formal **verification**: obtain a formal proof for the specification.

- The word **formal** means we use **mathematical objects** to model the system, both for specifying properties and for obtaining proofs.
- Some examples of used mathematical models: finite state machines, Petri nets, program semantics, process algebras, logics (classical, modal, temporal), etc.

Trial-and-error verification	Formal verification
<p>100 % confidence never reached</p> <p>Keypoint: good design of test cases</p> <p>We always depend on a program</p> <p>Efficiency = execution time</p>	<p>Mathematical methods</p> <p>Keypoint: good formulation of properties to prove</p> <p>We can work with an algorithm</p> <p>Efficiency = complexity</p>

Warning: tests are still necessary for **validation**. We can prove that a property holds, but perhaps it's not the right property to be proved!

- The ideal of **Formal Verification**
Program + **formulas** \longrightarrow Correct?
 - ▶ Yes : **correctness proof**
 - ▶ No : **counterexample**
 - ▶ ?? : sometimes we may have **no answer!**



Alan Turing
(1912 – 1952)

No Turing Award
but he's Turing!

Halting problem [Turing 1936] is **undecidable**:
there exists no algorithm to decide
if any arbitrary pair program+input
will eventually halt or run forever.

There are two main approaches to formal verification

1. **Theorem proving**: uses logical inference to prove the verification conditions.
 - ▶ **Semi-automated**: it usually requires **user supervision** or selection of **proof strategies**.
 - ▶ Best suited for **proving correctness** during the algorithm design.
 - ▶ Examples of theorem provers: Isabelle, ACL2, Coq, PVS.
 - ▶ In Coq, the proof is constructive: we can automatically **derive a correct program** in a functional language.

Formal verification approaches

There are two main approaches to formal verification

2. **Model checking**: systematically **exhaustive exploration** of the states and transitions in the model.

- ▶ When models are infinite, only possible if we can deal with a finite representation. With finite models, verification becomes decidable.
- ▶ Best suited for **finding counterexamples** on an already built system.
- ▶ Typically applied to **reactive systems**: they have infinite execution, but must satisfy some properties:
 - ★ **liveness**: something good eventually happens;
 - ★ **safety**: nothing bad ever happens.
- ▶ Properties are expressed using temporal logics.
- ▶ Those properties are checked using tools that (intelligently) explore the state space. These tools are called **model checkers**.

Model Checking main approaches



Amir Pnueli
(1941 – 2009)

Turing Award 1996



Edmund M. Clarke
(1945 –)

Turing Award 2007

Two main approaches

- **Linear Temporal Logic** (LTL) proposed by Pnueli in the 70's. It is used by the **SPIN** model checker. More oriented to (concurrent) software verification.
- **Computation Tree Logic** (CTL) proposed by Clarke and Emerson. It constitutes the basis of **SMV**, **NuMV**, **nuXmv** model checkers. More oriented to circuit verification.

Model Checking main approaches



Edmund M. Clarke
(1945 –)

Turing Award 2007

Exercise: watch Clarke's **invited talk on model checking**
at **Vienna Summer of Logic 2014**

<https://vimeo.com/103456257>